

**SIDDHARTH INSTITUTE OF ENGINEERING & TECHNOLOGY:: PUTTUR**  
 (AUTONOMOUS)

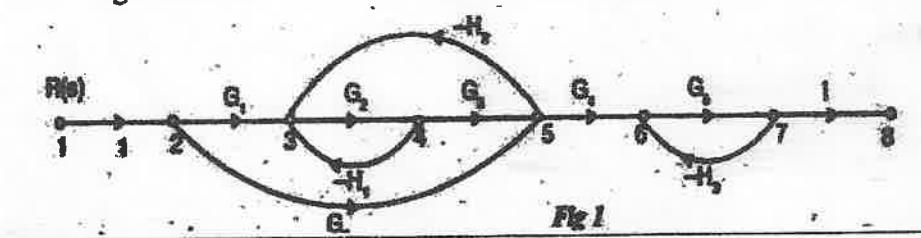
**B.Tech II Year II Semester Regular & Supplementary Examinations August-2023**  
**CONTROL SYSTEMS**  
**(Electronics & Communication Engineering)**

**Time: 3 Hours****Max. Marks: 60**(Answer all Five Units  $5 \times 12 = 60$  Marks)**UNIT-I**

- 1 a Compare open loop and closed loop control systems based on different aspects. CO1 L2 6M  
 b Distinguish between Block diagram Reduction Technique and Signal Flow Graph. CO1 L4 6M

**OR**

- 2 Find the overall transfer function of the system whose signal flow graph is shown in fig 1. CO2 L4 12M

**UNIT-II**

- 3 a Measurements conducted on a servo mechanism, show the system response to be  $c(t) = 1 + 0.2e^{-60t} - 1.2e^{-10t}$ . When subject to a unit step input. Obtain an expression for closed loop transfer function, determine the undamped natural frequency, damping ratio? CO3 L4 8M  
 b What is the characteristic equation? List the significance of characteristic equation. CO3 L1 4M

**OR**

- 4 Define steady state error. Derive the static error components for Type 0, Type 1 & Type 2 systems. CO3 L2 12M

**UNIT-III**

- 5 With the help of Routh's stability criterion determine the stability of the following systems represented by the characteristic equations:  
 $s^5 + s^4 + 2s^3 + 2s^2 + 3s + 5 = 0$   
 $9s^5 - 20s^4 + 10s^3 - s^2 - 9s - 10 = 0$

**OR**

- 6 Explain the procedure for constructing root locus. CO5 L2 12M

**UNIT-IV**

- 7 List out the frequency domain specifications and derive the expressions for resonant peak. CO4 L2 12M

**OR**

- 8 a Define and derive the expression for resonant frequency CO4 L1 6M  
 b Given  $\xi = 0.7$  and  $\omega_n = 10$  rad/sec. Find resonant peak, resonant frequency and bandwidth. CO4 L3 6M

**UNIT-V**

- 9 a Explain the properties of STM. CO6 L2 6M  
 b Derive the expression for the transfer function and poles of the system from the state model.  $X = Ax + Bu$  and  $y = Cx + Du$  CO6 L3 6M

**OR**

- 10 Find state variable representation of an armature controlled D.C.motor. CO6 L2 12M

**\*\*\* END \*\*\***

